

# Factor Analysis, Probabilistic PCA, and Variational Inference

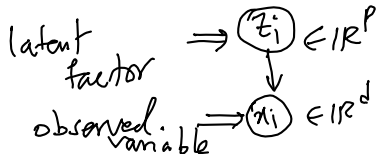
Statistical Machine Learning (ENGG\*6600\*02)

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## Variational Inference

# Variational Inference



- Consider a dataset  $\{\mathbf{x}_i\}_{i=1}^n$ . Assume that every data point  $\mathbf{x}_i \in \mathbb{R}^d$  is generated from a latent variable  $\mathbf{z}_i \in \mathbb{R}^p$ . This latent variable has a prior distribution  $\mathbb{P}(\mathbf{z}_i)$ . According to Bayes' rule, we have:

$$\mathbb{P}(\mathbf{z}_i | \mathbf{x}_i) = \frac{\mathbb{P}(\mathbf{x}_i | \mathbf{z}_i) \mathbb{P}(\mathbf{z}_i)}{\mathbb{P}(\mathbf{x}_i)} \quad (1)$$

- Let  $\mathbb{P}(\mathbf{z}_i)$  be an arbitrary distribution denoted by  $q(\mathbf{z}_i)$ . Suppose the parameter of conditional distribution of  $\mathbf{z}_i$  on  $\mathbf{x}_i$  is denoted by  $\theta$ ; hence,  $\mathbb{P}(\mathbf{z}_i | \mathbf{x}_i) = \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \theta)$ . Therefore, we can say:

$$\star \quad \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \theta) = \frac{\mathbb{P}(\mathbf{x}_i | \mathbf{z}_i, \theta) \mathbb{P}(\mathbf{z}_i | \theta)}{\mathbb{P}(\mathbf{x}_i | \theta)} \quad (2)$$

$$\mathbb{P}(\mathbf{z}_i, \mathbf{x}_i | \theta) = \mathbb{P}(\mathbf{x}_i, \mathbf{z}_i | \theta)$$

# Variational Inference

- Consider the Kullback-Leibler (KL) divergence [1] between the prior probability of the latent variable and the posterior of the latent variable:

$$\begin{aligned}
 & \star \text{KL}(q(z_i) \parallel \mathbb{P}(z_i | x_i, \theta)) \stackrel{(a)}{=} \int q(z_i) \log \left( \frac{q(z_i)}{\mathbb{P}(z_i | x_i, \theta)} \right) dz_i \\
 & = \int q(z_i) (\log(q(z_i)) - \log(\mathbb{P}(z_i | x_i, \theta))) dz_i \\
 & \stackrel{(2)}{=} \int q(z_i) (\log(q(z_i)) - \log(\mathbb{P}(x_i | z_i, \theta)) - \log(\mathbb{P}(z_i | \theta)) + \log(\mathbb{P}(x_i | \theta))) dz_i \\
 & \stackrel{(b)}{=} \underbrace{\log(\mathbb{P}(x_i | \theta))}_{\uparrow} + \int q(z_i) (\log(q(z_i)) - \log(\mathbb{P}(x_i | z_i, \theta)) - \log(\mathbb{P}(z_i | \theta))) dz_i \\
 & = \log(\mathbb{P}(x_i | \theta)) + \int q(z_i) \log \left( \frac{q(z_i)}{\mathbb{P}(x_i | z_i, \theta) \mathbb{P}(z_i | \theta)} \right) dz_i \leftarrow \\
 & = \log(\mathbb{P}(x_i | \theta)) + \int q(z_i) \log \left( \frac{q(z_i)}{\mathbb{P}(x_i, z_i | \theta)} \right) dz_i \\
 & = \log(\mathbb{P}(x_i | \theta)) + \text{KL}(q(z_i) \parallel \mathbb{P}(x_i, z_i | \theta)), \leftarrow
 \end{aligned}$$

$\log\left(\frac{a}{b}\right) = \log a - \log b$

where (a) is for definition of KL divergence and (b) is because  $\log(\mathbb{P}(x_i | \theta))$  is independent of  $z_i$  and comes out of integral and  $\int dz_i = 1$ .

- Hence:

$$\longrightarrow \log(\mathbb{P}(x_i | \theta)) = \text{KL}(q(z_i) \parallel \mathbb{P}(z_i | x_i, \theta)) - \text{KL}(q(z_i) \parallel \mathbb{P}(x_i, z_i | \theta)). \quad (3)$$

# Variational Inference

- We found:

$$\star \log(\mathbb{P}(\mathbf{x}_i | \theta)) = \text{KL}(q(\mathbf{z}_i) \parallel \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \theta)) \underbrace{- \mathcal{L}(q, \theta)}_{\mathcal{L}(q, \theta)}.$$

- We define the **Evidence Lower Bound (ELBO)** as:

$$\star \mathcal{L}(q, \theta) := \underbrace{-\text{KL}(q(\mathbf{z}_i) \parallel \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \theta))}_{\mathcal{L}(q, \theta)}. \quad (4)$$

So:

$$\star \log(\mathbb{P}(\mathbf{x}_i | \theta)) = \text{KL}(q(\mathbf{z}_i) \parallel \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \theta)) + \mathcal{L}(q, \theta).$$

- Therefore:

$$\star \mathcal{L}(q, \theta) = \underbrace{\log(\mathbb{P}(\mathbf{x}_i | \theta))}_{\text{evidence}} - \underbrace{\text{KL}(q(\mathbf{z}_i) \parallel \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \theta))}_{\geq 0}. \quad (5)$$

- As the second term is negative with its minus, the ELBO is a lower bound on the log likelihood of data:

$$\mathcal{L}(q, \theta) \leq \log(\mathbb{P}(\mathbf{x}_i | \theta)). \quad (6)$$

The likelihood  $\mathbb{P}(\mathbf{x}_i | \theta)$  is also referred to as the **evidence**.

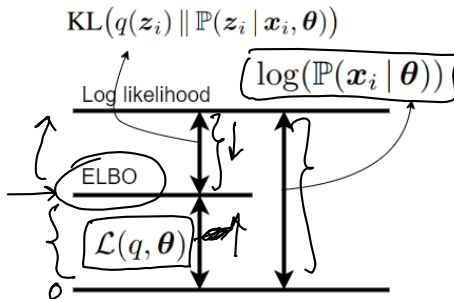
- Note that this lower bound gets tight when:

$$\begin{aligned} \mathcal{L}(q, \theta) &\approx \log(\mathbb{P}(\mathbf{x}_i | \theta)) \Rightarrow 0 \leq \text{KL}(q(\mathbf{z}_i) \parallel \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \theta)) \stackrel{\text{set}}{=} 0 \\ &\Rightarrow q(\mathbf{z}_i) = \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \theta). \end{aligned} \quad (7)$$

# Variational Inference

- We found:

$$\log(\mathbb{P}(\mathbf{x}_i | \boldsymbol{\theta})) = \text{KL}(q(\mathbf{z}_i) \parallel \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \boldsymbol{\theta})) + \mathcal{L}(q, \boldsymbol{\theta}).$$



# Expectation Maximization in Variational Inference

- According to MLE, we want to maximize the log-likelihood of data. According to Eq. (6):

$$\mathcal{L}(q, \theta) \leq \log(\mathbb{P}(\mathbf{x}_i | \theta)), \quad \leftarrow$$

maximizing the ELBO will also maximize the log-likelihood.

- The Eq. (6) holds for any prior distribution  $q$ . We want to find the best distribution to maximize the lower bound.
- Hence, EM for variational inference is performed iteratively as:

$$\text{E-step: } q^{(t)} := \arg \max_q \mathcal{L}(q, \theta^{(t-1)}), \quad (8)$$

$$\text{M-step: } \theta^{(t)} := \arg \max_{\theta} \mathcal{L}(q^{(t)}, \theta), \quad (9)$$

where  $t$  denotes the iteration index.

MLE on  $\mathcal{L}(q, \theta)$

# Expectation Maximization in Variational Inference

- **E-step in EM for Variational Inference:** The E-step is:

$$\begin{aligned} \max_q \mathcal{L}(q, \theta^{(t-1)}) &\stackrel{(5)}{=} \max_q \log(\mathbb{P}(\mathbf{x}_i | \theta^{(t-1)})) + \max_q (-\text{KL}(q(\mathbf{z}_i) \| \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \theta^{(t-1)}))) \\ &= \max_q \log(\mathbb{P}(\mathbf{x}_i | \theta^{(t-1)})) + \min_q \text{KL}(q(\mathbf{z}_i) \| \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \theta^{(t-1)})). \end{aligned}$$

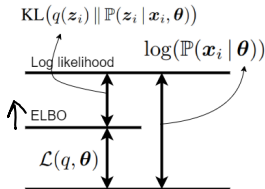
- The second term is always non-negative; hence, its minimum is zero:

$$\text{KL}(q(\mathbf{z}_i) \| \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \theta^{(t-1)})) \stackrel{\text{set}}{=} 0 \implies q(\mathbf{z}_i) = \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \theta^{(t-1)}),$$

which was already found in Eq. (7). Thus, the E-step assigns:

$$q^{(t)}(\mathbf{z}_i) \leftarrow \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \theta^{(t-1)}). \quad (10)$$

- In other words, in the figure, it pushes the middle line toward the above line by maximizing the ELBO.





# Expectation Maximization in Variational Inference

- M-step in EM for Variational Inference: The M-step is:

$$\begin{aligned}\max_{\theta} \mathcal{L}(q^{(t)}, \theta) &\stackrel{(4)}{=} \max_{\theta} \left( - \text{KL}(q^{(t)}(z_i) \parallel \mathbb{P}(x_i, z_i \mid \theta)) \right) \\ &\stackrel{(a)}{=} \max_{\theta} \left[ - \int q^{(t)}(z_i) \log \left( \frac{q^{(t)}(z_i)}{\mathbb{P}(x_i, z_i \mid \theta)} \right) dz_i \right] \\ &= \max_{\theta} \int q^{(t)}(z_i) \log(\mathbb{P}(x_i, z_i \mid \theta)) dz_i - \max_{\theta} \int q^{(t)}(z_i) \log(q^{(t)}(z_i)) dz_i,\end{aligned}$$

where (a) is for definition of KL divergence.

- The second term is constant w.r.t.  $\theta$ . Hence:

$$\begin{aligned}\max_{\theta} \mathcal{L}(q^{(t)}, \theta) &= \max_{\theta} \int q^{(t)}(z_i) \log(\mathbb{P}(x_i, z_i \mid \theta)) dz_i \\ &\stackrel{(a)}{=} \max_{\theta} \mathbb{E}_{q^{(t)}(z_i)} [\log \mathbb{P}(x_i, z_i \mid \theta)],\end{aligned}$$

where (a) is because of definition of expectation. Thus, the M-step assigns:

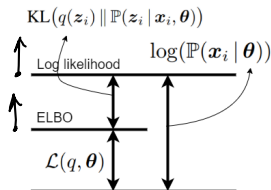
$$\theta^{(t)} \leftarrow \arg \max_{\theta} \mathbb{E}_{q^{(t)}(z_i)} [\log \mathbb{P}(x_i, z_i \mid \theta)]. \quad (11)$$

# Expectation Maximization in Variational Inference

- We found:

$$\theta^{(t)} \leftarrow \arg \max_{\theta} \mathbb{E}_{\sim q^{(t)}(z_i)} [\log \mathbb{P}(\mathbf{x}_i, \mathbf{z}_i | \theta)].$$

- In other words, in the figure, it pushes the above line higher.



- The E-step and M-step together somehow play a game where the E-step tries to reach the middle line (or the ELBO) to the log-likelihood and the M-step tries to increase the above line (or the log-likelihood). This procedure is done repeatedly so the two steps help each other improve to higher values.
- To summarize, the EM in variational inference is:

$$\left\{ \begin{array}{l} q^{(t)}(z_i) \leftarrow \mathbb{P}(z_i | \mathbf{x}_i, \theta^{(t-1)}), \\ \theta^{(t)} \leftarrow \arg \max_{\theta} \mathbb{E}_{\sim q^{(t)}(z_i)} [\log \mathbb{P}(\mathbf{x}_i, \mathbf{z}_i | \theta)]. \end{array} \right. \quad (12)$$

$$(13)$$

# Expectation Maximization in Variational Inference

- It is noteworthy that, in variational inference, sometimes, the parameter  $\theta$  is absorbed into the latent variable  $\mathbf{z}_i$ .
- According to the chain rule, we have:

$$\mathbb{P}(\mathbf{x}_i, \mathbf{z}_i, \theta) = \underbrace{\mathbb{P}(\mathbf{x}_i)}_{\text{data}} \underbrace{\mathbb{P}(\mathbf{x}_i | \mathbf{z}_i, \theta)}_{\text{likelihood}} \underbrace{\mathbb{P}(\mathbf{z}_i | \theta)}_{\text{prior}} \underbrace{\mathbb{P}(\theta)}_{\text{hyperprior}}.$$

- Considering the term  $\mathbb{P}(\mathbf{z}_i | \theta) \mathbb{P}(\theta)$  as one probability term, we have:

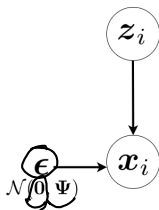
$$\mathbb{P}(\mathbf{x}_i, \mathbf{z}_i) = \mathbb{P}(\mathbf{x}_i | \mathbf{z}_i) \mathbb{P}(\mathbf{z}_i),$$

where the parameter  $\theta$  disappears because of absorption.

## Factor Analysis

# Factor Analysis

- Factor analysis [2, 3, 4, 5] is one of the simplest and most fundamental generative models.
- Factor analysis assumes that every data point  $\mathbf{x}_i \in \mathbb{R}^d$  is generated from a latent variable  $\mathbf{z}_i \in \mathbb{R}^p$ . The latent variable is also referred to as the latent factor; hence, the name of factor analysis comes from the fact that it analyzes the latent factors.
- In factor analysis, we assume that the data point  $\mathbf{x}_i$  is obtained through the following steps: (1) by linear projection of the  $p$ -dimensional  $\mathbf{z}_i$  onto a  $d$ -dimensional space by projection matrix  $\mathbf{\Lambda} \in \mathbb{R}^{d \times p}$ , then (2) applying some linear translation, and finally (3) adding a Gaussian noise  $\epsilon \in \mathbb{R}^d$  with covariance matrix  $\Psi \in \mathbb{R}^{d \times d}$ .
- Note that as the noises in different dimensions are independent, the covariance matrix  $\Psi$  is diagonal.
- Factor analysis can be illustrated as a graphical model [6] where the visible data variable is conditioned on the latent variable and the noise random variable.



# Factor Analysis

- For simplicity, the prior distribution of the latent variable can be assumed to be a multivariate Gaussian distribution:

$$\mathbb{P}(\mathbf{z}_i) = \mathcal{N}(\mathbf{z}_i | \underbrace{\boldsymbol{\mu}_0}_{\text{mean}}, \underbrace{\boldsymbol{\Sigma}_0}_{\text{covariance}}) = \frac{1}{\sqrt{(2\pi)^p |\boldsymbol{\Sigma}_0|}} \exp\left(-\frac{(\mathbf{z}_i - \boldsymbol{\mu}_0)^\top \boldsymbol{\Sigma}_0^{-1} (\mathbf{z}_i - \boldsymbol{\mu}_0)}{2}\right), \quad (14)$$

where  $\boldsymbol{\mu}_0 \in \mathbb{R}^p$  and  $\boldsymbol{\Sigma}_0 \in \mathbb{R}^{p \times p}$  are the mean and the covariance matrix of  $\mathbf{z}_i$  and  $|\cdot|$  is the determinant of matrix.

- $\mathbf{x}_i$  is obtained through (1) the linear projection of  $\mathbf{z}_i$  by  $\boldsymbol{\Lambda} \in \mathbb{R}^{d \times p}$ , (2) applying some linear translation, and (3) adding a Gaussian noise  $\epsilon \in \mathbb{R}^d$  with covariance  $\boldsymbol{\Psi} \in \mathbb{R}^{d \times d}$ .
- Hence, the data point  $\mathbf{x}_i$  has a conditional multivariate Gaussian distribution given the latent variable; its conditional likelihood is:

$$\mathbb{P}(\mathbf{x}_i | \mathbf{z}_i) = \mathbb{P}(\mathbf{x}_i | \mathbf{z}_i, \boldsymbol{\Lambda}, \underbrace{\boldsymbol{\mu}}_{\text{translation}}, \underbrace{\boldsymbol{\Psi}}_{\text{covariance}}) = \mathcal{N}(\boldsymbol{\Lambda} \mathbf{z}_i + \boldsymbol{\mu}, \boldsymbol{\Psi}), \quad (15)$$

where  $\boldsymbol{\mu}$ , which is the translation vector, is the mean of data  $\{\mathbf{x}_i\}_{i=1}^n$ :

$$\mathbb{R}^d \ni \boldsymbol{\mu} := \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i. \quad (16)$$

# Factor Analysis

- The marginal distribution of  $\mathbf{x}_i$  is:

$$\begin{aligned}
 \mathbb{P}(\mathbf{x}_i) &= \int \mathbb{P}(\mathbf{x}_i | \mathbf{z}_i) \mathbb{P}(\mathbf{z}_i) d\mathbf{z}_i \implies \mathbb{P}(\mathbf{x}_i | \mathbf{\Lambda}, \boldsymbol{\mu}, \boldsymbol{\Psi}) = \int \mathbb{P}(\mathbf{x}_i | \mathbf{z}_i, \mathbf{\Lambda}, \boldsymbol{\mu}, \boldsymbol{\Psi}) \mathbb{P}(\mathbf{z}_i | \boldsymbol{\mu}_0, \boldsymbol{\Sigma}_0) d\mathbf{z}_i \\
 &\stackrel{(a)}{=} \mathcal{N}(\underbrace{\mathbf{\Lambda}\boldsymbol{\mu}_0 + \boldsymbol{\mu}}_{\hat{\boldsymbol{\mu}}}, \underbrace{\boldsymbol{\Psi} + \mathbf{\Lambda}\boldsymbol{\Sigma}_0\mathbf{\Lambda}^T}_{\hat{\boldsymbol{\Lambda}}}) \rightarrow \mathbf{\Lambda} \underbrace{\boldsymbol{\Sigma}_0^{-1/2}}_{\mathbf{\Sigma}_0^{-1/2}} \underbrace{\boldsymbol{\Sigma}_0^{1/2}}_{\mathbf{\Sigma}_0^{1/2}} \mathbf{\Lambda}^T
 \end{aligned}
 \tag{17}$$

$$= \mathcal{N}(\hat{\boldsymbol{\mu}}, \boldsymbol{\Psi} + \hat{\boldsymbol{\Lambda}}), \tag{18}$$

where  $\mathbb{R}^d \ni \hat{\boldsymbol{\mu}} := \mathbf{\Lambda}\boldsymbol{\mu}_0 + \boldsymbol{\mu}$ ,  $\mathbb{R}^{d \times d} \ni \hat{\boldsymbol{\Lambda}} := \mathbf{\Lambda}\boldsymbol{\Sigma}_0^{(1/2)}$ , and (a) is because mean is linear and variance is quadratic so the mean and variance of projection are applied linearly and quadratically, respectively.

- As the mean  $\hat{\boldsymbol{\mu}}$  and covariance  $\hat{\boldsymbol{\Lambda}}$  are needed to be learned, we can absorb  $\boldsymbol{\mu}_0$  and  $\boldsymbol{\Sigma}_0$  into  $\boldsymbol{\mu}$  and  $\boldsymbol{\Lambda}$  and assume that  $\boldsymbol{\mu}_0 = \mathbf{0}$  and  $\boldsymbol{\Sigma}_0 = \mathbf{I}$ .
- In summary, factor analysis assumes every data point  $\mathbf{x}_i \in \mathbb{R}^d$  is obtained by projecting a latent variable  $\mathbf{z}_i \in \mathbb{R}^p$  onto a  $d$ -dimensional space by projection matrix  $\mathbf{\Lambda} \in \mathbb{R}^{d \times p}$  and translating it by  $\boldsymbol{\mu} \in \mathbb{R}^d$  and finally adding some Gaussian noise  $\epsilon \in \mathbb{R}^d$  (whose dimensions are independent) as:

$$\mathbf{x}_i := \mathbf{\Lambda}\mathbf{z}_i + \boldsymbol{\mu} + \epsilon, \tag{19}$$

$$\mathbb{P}(\mathbf{z}_i) = \mathcal{N}(\mathbf{0}, \mathbf{I}), \tag{20}$$

$$\mathbb{P}(\epsilon) = \mathcal{N}(\mathbf{0}, \boldsymbol{\Psi}). \tag{21}$$

# Factor Analysis

- The joint distribution of  $\mathbf{x}_i$  and  $\mathbf{z}_i$  is:

$$\longrightarrow \mathbf{y}_i := \begin{bmatrix} \mathbf{x}_i \\ \mathbf{z}_i \end{bmatrix} \sim \mathcal{N}(\underbrace{\boldsymbol{\mu}_y}, \underbrace{\boldsymbol{\Sigma}_y}). \quad (22)$$

- The expectation of  $\mathbf{x}_i$  is:

$$\mathbb{E}[\mathbf{x}_i] \stackrel{(19)}{=} \mathbb{E}[\boldsymbol{\Lambda} \mathbf{z}_i + \boldsymbol{\mu} + \boldsymbol{\epsilon}] = \boldsymbol{\Lambda} \mathbb{E}[\mathbf{z}_i] + \boldsymbol{\mu} + \mathbb{E}[\boldsymbol{\epsilon}] \stackrel{(a)}{=} \boldsymbol{\mu}, \quad (23)$$

where (a) is because of Eqs. (20) and (21).

- Hence:

$$\boldsymbol{\mu}_y := \begin{bmatrix} \boldsymbol{\mu}_x \\ \boldsymbol{\mu}_z \end{bmatrix} \stackrel{(a)}{=} \begin{bmatrix} \boldsymbol{\mu} \\ \mathbf{0} \end{bmatrix}, \quad (24)$$

where (a) is because of Eqs. (20) and (23).



# Factor Analysis

- Lemma:

## Lemma

Consider two random variables  $\mathbf{x}_i \in \mathbb{R}^d$  and  $\mathbf{z}_i \in \mathbb{R}^p$  and let  $\mathbf{y}_i := [\mathbf{x}_i^\top, \mathbf{z}_i^\top]^\top \in \mathbb{R}^{d+p}$ . Assume that  $\mathbf{x}_i$  and  $\mathbf{z}_i$  are jointly multivariate Gaussian; hence, the variable  $\mathbf{y}_i$  has a multivariate Gaussian distribution, i.e.,  $\mathbf{y}_i \sim \mathcal{N}(\boldsymbol{\mu}_y, \boldsymbol{\Sigma}_y)$ . The mean and covariance can be decomposed as:

$$\left\{ \begin{array}{l} \boldsymbol{\mu}_y = [\boldsymbol{\mu}^\top, \boldsymbol{\mu}_0^\top]^\top \in \mathbb{R}^{d+p}, \end{array} \right. \quad (25)$$

$$\left\{ \begin{array}{l} \boldsymbol{\Sigma}_y = \begin{bmatrix} \boldsymbol{\Sigma}_{11} & \boldsymbol{\Sigma}_{12} \\ \boldsymbol{\Sigma}_{21} & \boldsymbol{\Sigma}_{22} \end{bmatrix} \in \mathbb{R}^{(d+p) \times (d+p)}, \end{array} \right. \quad (26)$$

where  $\boldsymbol{\mu} \in \mathbb{R}^d$ ,  $\boldsymbol{\mu}_0 \in \mathbb{R}^p$ ,  $\boldsymbol{\Sigma}_{11} \in \mathbb{R}^{d \times d}$ ,  $\boldsymbol{\Sigma}_{22} \in \mathbb{R}^{p \times p}$ ,  $\boldsymbol{\Sigma}_{12} \in \mathbb{R}^{d \times p}$ , and  $\boldsymbol{\Sigma}_{21} = \boldsymbol{\Sigma}_{12}^\top \in \mathbb{R}^{p \times d}$ .

# Factor Analysis

- Lemma [7]:

## Lemma

$$\left. \begin{aligned} \mathbb{R}^d \ni \underline{\mu_{x|z}} &:= \underline{\mu + \Sigma_{12}\Sigma_{22}^{-1}(z_i - \mu_0)}, \\ \mathbb{R}^{d \times d} \ni \underline{\Sigma_{x|z}} &:= \underline{\Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21}}, \end{aligned} \right\} \quad \begin{aligned} (27) \\ (28) \end{aligned}$$

and likewise for  $z_i|x_i \sim \mathcal{N}(\underline{\mu_{z|x}}, \underline{\Sigma_{z|x}})$ :

$$\mathbb{R}^p \ni \underline{\mu_{z|x}} := \underline{\mu_0 + \Sigma_{21}\Sigma_{11}^{-1}(x_i - \mu)}, \quad (29)$$

$$\mathbb{R}^{p \times p} \ni \underline{\Sigma_{z|x}} := \underline{\Sigma_{22} - \Sigma_{21}\Sigma_{11}^{-1}\Sigma_{12}}. \quad (30)$$

# Factor Analysis

- According to Eq. (20), we have  $\Sigma_{22} = \Sigma_z = I$ . According to Eq. (19), we have:

$$\begin{aligned}
 \Sigma_{11} &= \Sigma_x = \mathbb{E}[(x_i - \mu)(x_i - \mu)^T], \\
 &= \mathbb{E}[(\Lambda z_i + \mu + \epsilon - \mu)(\Lambda z_i + \mu + \epsilon - \mu)^T] \\
 &= \mathbb{E}[\Lambda z_i z_i^T \Lambda^T + \epsilon z_i^T \Lambda^T + \Lambda z_i \epsilon^T + \epsilon \epsilon^T] \\
 &= \Lambda \mathbb{E}[z_i z_i^T] \Lambda^T + \mathbb{E}[\epsilon] \mathbb{E}[z_i]^T \Lambda^T + \Lambda \mathbb{E}[z_i] \mathbb{E}[\epsilon]^T + \mathbb{E}[\epsilon \epsilon^T] \\
 &\stackrel{(a)}{=} \Lambda \Lambda^T + \mathbf{0} + \mathbf{0} + \Psi = \Lambda \Lambda^T + \Psi,
 \end{aligned} \tag{31}$$

where (a) is because of Eqs. (20) and (21).

- Moreover, we have:

$$\begin{aligned}
 \Sigma_{12} &= \Sigma_{xz} = \mathbb{E}[(x_i - \mu)(z_i - \mu_0)^T] \\
 &\stackrel{(a)}{=} \mathbb{E}[(\Lambda z_i + \mu + \epsilon - \mu)(z_i - \mathbf{0})^T] \\
 &\stackrel{(b)}{=} \Lambda \mathbb{E}[z_i z_i^T] + \mathbb{E}[\epsilon] \mathbb{E}[z_i]^T = \Lambda I + (\mathbf{0} \mathbf{0}^T) = \Lambda,
 \end{aligned} \tag{32}$$

where (a) is because of Eqs. (19) and (20) and (b) is because  $z_i$  and  $\epsilon$  are independent.

- We also have  $\Sigma_{21} = \Sigma_{12}^T = \Lambda^T$ . Therefore:

$$\begin{bmatrix} x_i \\ z_i \end{bmatrix} \sim \mathcal{N} \left( \begin{bmatrix} \mu \\ \mathbf{0} \end{bmatrix}, \begin{bmatrix} \Lambda \Lambda^T + \Psi & \Lambda \\ \Lambda^T & I \end{bmatrix} \right). \tag{33}$$

# Factor Analysis

- Hence, the marginal distribution of data point  $\mathbf{x}_i$  is:

$$\mathbb{P}(\mathbf{x}_i) = \mathbb{P}(\mathbf{x}_i | \mathbf{\Lambda}, \boldsymbol{\mu}, \boldsymbol{\Psi}) = \mathcal{N}(\boldsymbol{\mu}, \mathbf{\Lambda}\mathbf{\Lambda}^\top + \boldsymbol{\Psi}). \quad (34)$$

According to Eqs. (29) and (30) [Lemma], the posterior or the conditional distribution of latent variable given data is:

$$\underbrace{q(\mathbf{z}_i)} \stackrel{(12)}{=} \underbrace{\mathbb{P}(\mathbf{z}_i | \mathbf{x}_i)} = \mathbb{P}(\mathbf{z}_i | \mathbf{x}_i, \mathbf{\Lambda}, \boldsymbol{\mu}, \boldsymbol{\Psi}) = \mathcal{N}(\underbrace{\boldsymbol{\mu}_{z|x}}, \underbrace{\boldsymbol{\Sigma}_{z|x}}), \quad (35)$$

where:

$$\left\{ \begin{array}{l} \mathbb{R}^p \ni \boldsymbol{\mu}_{z|x} := \mathbf{\Lambda}^\top (\mathbf{\Lambda}\mathbf{\Lambda}^\top + \boldsymbol{\Psi})^{-1} (\mathbf{x}_i - \boldsymbol{\mu}), \\ \mathbb{R}^{p \times p} \ni \boldsymbol{\Sigma}_{z|x} := \mathbf{I} - \mathbf{\Lambda}^\top (\mathbf{\Lambda}\mathbf{\Lambda}^\top + \boldsymbol{\Psi})^{-1} \mathbf{\Lambda}. \end{array} \right. \quad (36)$$

$$(37)$$

- Recall that the conditional distribution of data given the latent variable, i.e.  $\mathbb{P}(\mathbf{x}_i | \mathbf{z}_i)$ , was introduced in Eq. (15):

$$\mathbb{P}(\mathbf{x}_i | \mathbf{z}_i) = \mathbb{P}(\mathbf{x}_i | \mathbf{z}_i, \mathbf{\Lambda}, \boldsymbol{\mu}, \boldsymbol{\Psi}) = \mathcal{N}(\underbrace{\mathbf{\Lambda}\mathbf{z}_i + \boldsymbol{\mu}}, \boldsymbol{\Psi}).$$

If data  $\{\mathbf{x}_i\}_{i=1}^n$  are centered, i.e.  $\boldsymbol{\mu} = \mathbf{0}$ , the marginal of data, Eq. (34), and the likelihood of data, Eq. (15), become:

$$\left\{ \begin{array}{l} \mathbb{P}(\mathbf{x}_i | \mathbf{\Lambda}, \boldsymbol{\Psi}) = \mathcal{N}(\underbrace{\mathbf{0}} \boldsymbol{\Psi} + \mathbf{\Lambda}\mathbf{\Lambda}^\top), \\ \mathbb{P}(\mathbf{x}_i | \mathbf{z}_i, \mathbf{\Lambda}, \boldsymbol{\Psi}) = \mathcal{N}(\mathbf{\Lambda}\mathbf{z}_i, \boldsymbol{\Psi}), \end{array} \right. \quad (38)$$

$$(39)$$

respectively. In some works, people center the data as a pre-processing to factor analysis.

# Factor Analysis

- We can find the parameters  $\Lambda$  and  $\Psi$  using Expectation Maximization.
- See our tutorial "Factor analysis, probabilistic principal component analysis, variational inference, and variational autoencoder: Tutorial and survey" [8] for the details of EM steps in factor analysis.

## **Probabilistic Principal Component Analysis**

# Probabilistic Principal Component Analysis

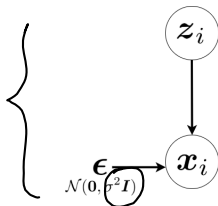
- **Probabilistic PCA (PPCA)** (1997-1999) [9, 10] is a special case of factor analysis where the variance of noise is equal in all dimensions of data space with covariance between dimensions, i.e.:

$$\Psi = \sigma^2 I. \quad (40)$$

- In other words, PPCA considers an isotropic noise in its formulation. Therefore, Eq. (21) is simplified to:

$$\mathbb{P}(\epsilon) = \mathcal{N}(\mathbf{0}, \sigma^2 I). \quad (41)$$

- Because of having zero covariance of noise between different dimensions, PPCA assumes that the data points are **independent** of each other given latent variables.
- PPCA can be illustrated as a graphical model, where the visible data variable is conditioned on the latent variable and the isotropic noise random variable.



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- As PPCA is a special case of factor analysis, it also is solved using EM. Similar to factor analysis, it can be solved iteratively using EM [9].
- However, one can also find a closed-form solution to its EM approach [10]. Hence, by restricting the noise covariance to be isotropic, its solution becomes simpler and closed-form.
- We can find the parameters  $\Lambda$  and  $\sigma$  using Expectation Maximization.
- See our tutorial “Factor analysis, probabilistic principal component analysis, variational inference, and variational autoencoder: Tutorial and survey” [8] for the details of EM steps in PPCA.

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# Acknowledgment

- Some slides are based on our tutorial paper: “Factor analysis, probabilistic principal component analysis, variational inference, and variational autoencoder: Tutorial and survey” [8]
- Some slides of this slide deck are inspired by teachings of deep learning course at the Carnegie Mellon University (you can see their YouTube channel).
- Factor analysis in sklearn: <https://scikit-learn.org/stable/modules/generated/sklearn.decomposition.FactorAnalysis.html>

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