# Factor Analysis, Probabilistic PCA, and Variational Inference

Statistical Machine Learning (ENGG\*6600\*08)

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• Consider a dataset  $\{x_i\}_{i=1}^n$ . Assume that every data point  $x_i \in \mathbb{R}^d$  is generated from a latent variable  $z_i \in \mathbb{R}^p$ . This latent variable has a prior distribution  $\mathbb{P}(z_i)$ . According to Bayes' rule, we have:

$$\mathbb{P}(\boldsymbol{z}_i | \boldsymbol{x}_i) = \frac{\mathbb{P}(\boldsymbol{x}_i | \boldsymbol{z}_i) \mathbb{P}(\boldsymbol{z}_i)}{\mathbb{P}(\boldsymbol{x}_i)}.$$
 (1)

Let P(z<sub>i</sub>) be an arbitrary distribution denoted by q(z<sub>i</sub>). Suppose the parameter of conditional distribution of z<sub>i</sub> on x<sub>i</sub> is denoted by θ; hence, P(z<sub>i</sub> | x<sub>i</sub>) = P(z<sub>i</sub> | x<sub>i</sub>, θ). Therefore, we can say:

$$\mathbb{P}(\mathbf{z}_i \mid \mathbf{x}_i, \boldsymbol{\theta}) = \frac{\mathbb{P}(\mathbf{x}_i \mid \mathbf{z}_i, \boldsymbol{\theta}) \mathbb{P}(\mathbf{z}_i \mid \boldsymbol{\theta})}{\mathbb{P}(\mathbf{x}_i \mid \boldsymbol{\theta})}.$$
(2)

• Consider the Kullback-Leibler (KL) divergence [1] between the prior probability of the latent variable and the posterior of the latent variable:

$$\begin{aligned} \mathsf{KL}(q(z_i) \parallel \mathbb{P}(z_i \mid \mathbf{x}_i, \theta)) &\stackrel{(a)}{=} \int q(z_i) \log \left(\frac{q(z_i)}{\mathbb{P}(z_i \mid \mathbf{x}_i, \theta)}\right) dz_i \\ &= \int q(z_i) \left( \log(q(z_i)) - \log(\mathbb{P}(z_i \mid \mathbf{x}_i, \theta)) \right) dz_i \\ &\stackrel{(2)}{=} \int q(z_i) \left( \log(q(z_i)) - \log(\mathbb{P}(\mathbf{x}_i \mid z_i, \theta)) - \log(\mathbb{P}(z_i \mid \theta)) + \log(\mathbb{P}(\mathbf{x}_i \mid \theta)) \right) dz_i \\ &\stackrel{(b)}{=} \log(\mathbb{P}(\mathbf{x}_i \mid \theta)) + \int q(z_i) \left( \log(q(z_i)) - \log(\mathbb{P}(\mathbf{x}_i \mid z_i, \theta)) - \log(\mathbb{P}(z_i \mid \theta)) \right) dz_i \\ &= \log(\mathbb{P}(\mathbf{x}_i \mid \theta)) + \int q(z_i) \log(\frac{q(z_i)}{\mathbb{P}(\mathbf{x}_i \mid z_i, \theta)\mathbb{P}(z_i \mid \theta)}) dz_i \\ &= \log(\mathbb{P}(\mathbf{x}_i \mid \theta)) + \int q(z_i) \log(\frac{q(z_i)}{\mathbb{P}(\mathbf{x}_i, z_i \mid \theta)}) dz_i \\ &= \log(\mathbb{P}(\mathbf{x}_i \mid \theta)) + \int q(z_i) \log(\frac{q(z_i)}{\mathbb{P}(\mathbf{x}_i, z_i \mid \theta)}) dz_i \end{aligned}$$

where (a) is for definition of KL divergence and (b) is because  $\log(\mathbb{P}(\mathbf{x}_i | \theta))$  is independent of  $\mathbf{z}_i$  and comes out of integral and  $\int d\mathbf{z}_i = 1$ .

Hence:

$$\log(\mathbb{P}(\mathbf{x}_i \mid \boldsymbol{\theta})) = \mathsf{KL}(q(\mathbf{z}_i) \parallel \mathbb{P}(\mathbf{z}_i \mid \mathbf{x}_i, \boldsymbol{\theta})) - \mathsf{KL}(q(\mathbf{z}_i) \parallel \mathbb{P}(\mathbf{x}_i, \mathbf{z}_i \mid \boldsymbol{\theta})).$$
(3)

We found:

$$\log(\mathbb{P}(\boldsymbol{x}_i \mid \boldsymbol{\theta})) = \mathsf{KL}(q(\boldsymbol{z}_i) \parallel \mathbb{P}(\boldsymbol{z}_i \mid \boldsymbol{x}_i, \boldsymbol{\theta})) - \mathsf{KL}(q(\boldsymbol{z}_i) \parallel \mathbb{P}(\boldsymbol{x}_i, \boldsymbol{z}_i \mid \boldsymbol{\theta})).$$

We define the Evidence Lower Bound (ELBO) as:

$$\mathcal{L}(q,\theta) := -\mathsf{KL}(q(\mathbf{z}_i) \| \mathbb{P}(\mathbf{x}_i, \mathbf{z}_i | \theta)).$$
(4)

So:

$$\log(\mathbb{P}(\boldsymbol{x}_i \mid \boldsymbol{\theta})) = \mathsf{KL}(q(\boldsymbol{z}_i) \parallel \mathbb{P}(\boldsymbol{z}_i \mid \boldsymbol{x}_i, \boldsymbol{\theta})) + \mathcal{L}(q, \boldsymbol{\theta}).$$

Therefore:

$$\mathcal{L}(q,\theta) = \log(\mathbb{P}(\mathbf{x}_i \mid \theta)) - \underbrace{\mathsf{KL}(q(\mathbf{z}_i) \parallel \mathbb{P}(\mathbf{z}_i \mid \mathbf{x}_i, \theta))}_{\geq 0}.$$
 (5)

 As the second term is negative with its minus, the ELBO is a lower bound on the log likelihood of data:

$$\mathcal{L}(\boldsymbol{q},\boldsymbol{\theta}) \leq \log(\mathbb{P}(\boldsymbol{x}_i \,|\, \boldsymbol{\theta})). \tag{6}$$

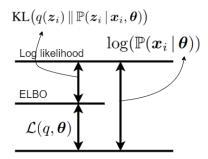
The likelihood  $\mathbb{P}(\mathbf{x}_i | \boldsymbol{\theta})$  is also referred to as the **evidence**.

• Note that this lower bound gets tight when:

$$\mathcal{L}(q,\theta) \approx \log(\mathbb{P}(\mathbf{x}_i \mid \theta)) \implies 0 \le \mathsf{KL}(q(\mathbf{z}_i) \parallel \mathbb{P}(\mathbf{z}_i \mid \mathbf{x}_i, \theta)) \stackrel{\text{set}}{=} 0$$
$$\implies q(\mathbf{z}_i) = \mathbb{P}(\mathbf{z}_i \mid \mathbf{x}_i, \theta).$$
(7)

• We found:

 $\log(\mathbb{P}(\boldsymbol{x}_i \mid \boldsymbol{\theta})) = \mathsf{KL}(q(\boldsymbol{z}_i) \parallel \mathbb{P}(\boldsymbol{z}_i \mid \boldsymbol{x}_i, \boldsymbol{\theta})) + \mathcal{L}(q, \boldsymbol{\theta}).$ 



According to MLE, we want to maximize the log-likelihood of data. According to Eq. (6):

$$\mathcal{L}(q, \theta) \leq \log(\mathbb{P}(\mathbf{x}_i \,|\, \theta)),$$

maximizing the ELBO will also maximize the log-likelihood.

- The Eq. (6) holds for any prior distribution q. We want to find the best distribution to maximize the lower bound.
- Hence, EM for variational inference is performed iteratively as:

E-step: 
$$q^{(t)} := \arg \max_{q} \mathcal{L}(q, \theta^{(t-1)}),$$
 (8)

$$\mathsf{M}\text{-step:} \quad \boldsymbol{\theta}^{(t)} := \arg \max_{\boldsymbol{\theta}} \quad \mathcal{L}(\boldsymbol{q}^{(t)}, \boldsymbol{\theta}), \tag{9}$$

where t denotes the iteration index.

• E-step in EM for Variational Inference: The E-step is:

$$\max_{q} \mathcal{L}(q, \theta^{(t-1)}) \stackrel{(5)}{=} \max_{q} \log(\mathbb{P}(\mathbf{x}_{i} \mid \theta^{(t-1)})) + \max_{q} \left(-\operatorname{KL}(q(\mathbf{z}_{i}) \parallel \mathbb{P}(\mathbf{z}_{i} \mid \mathbf{x}_{i}, \theta^{(t-1)}))\right)$$
$$= \max_{q} \log(\mathbb{P}(\mathbf{x}_{i} \mid \theta^{(t-1)})) + \min_{q} \operatorname{KL}(q(\mathbf{z}_{i}) \parallel \mathbb{P}(\mathbf{z}_{i} \mid \mathbf{x}_{i}, \theta^{(t-1)})).$$

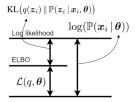
The second term is always non-negative; hence, its minimum is zero:

$$\mathsf{KL}(q(\boldsymbol{z}_i) \| \mathbb{P}(\boldsymbol{z}_i | \boldsymbol{x}_i, \boldsymbol{\theta}^{(t-1)})) \stackrel{\text{set}}{=} 0 \implies q(\boldsymbol{z}_i) = \mathbb{P}(\boldsymbol{z}_i | \boldsymbol{x}_i, \boldsymbol{\theta}^{(t-1)}),$$

which was already found in Eq. (7). Thus, the E-step assigns:

$$q^{(t)}(\boldsymbol{z}_i) \leftarrow \mathbb{P}(\boldsymbol{z}_i \,|\, \boldsymbol{x}_i, \boldsymbol{\theta}^{(t-1)}). \tag{10}$$

 In other words, in the figure, it pushes the middle line toward the above line by maximizing the ELBO.



• M-step in EM for Variational Inference: The M-step is:

$$\begin{split} \max_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{q}^{(t)}, \boldsymbol{\theta}) &\stackrel{(4)}{=} \max_{\boldsymbol{\theta}} \left( - \mathsf{KL}(\boldsymbol{q}^{(t)}(\boldsymbol{z}_i) \| \mathbb{P}(\boldsymbol{x}_i, \boldsymbol{z}_i | \boldsymbol{\theta})) \right) \\ &\stackrel{(a)}{=} \max_{\boldsymbol{\theta}} \left[ - \int \boldsymbol{q}^{(t)}(\boldsymbol{z}_i) \log\left(\frac{\boldsymbol{q}^{(t)}(\boldsymbol{z}_i)}{\mathbb{P}(\boldsymbol{x}_i, \boldsymbol{z}_i | \boldsymbol{\theta})}\right) d\boldsymbol{z}_i \right] \\ &= \max_{\boldsymbol{\theta}} \int \boldsymbol{q}^{(t)}(\boldsymbol{z}_i) \log(\mathbb{P}(\boldsymbol{x}_i, \boldsymbol{z}_i | \boldsymbol{\theta})) d\boldsymbol{z}_i - \max_{\boldsymbol{\theta}} \int \boldsymbol{q}^{(t)}(\boldsymbol{z}_i) \log(\boldsymbol{q}^{(t)}(\boldsymbol{z}_i)) d\boldsymbol{z}_i, \end{split}$$

where (a) is for definition of KL divergence.

• The second term is constant w.r.t.  $\theta$ . Hence:

$$\max_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{q}^{(t)}, \boldsymbol{\theta}) = \max_{\boldsymbol{\theta}} \int \boldsymbol{q}^{(t)}(\boldsymbol{z}_i) \log(\mathbb{P}(\boldsymbol{x}_i, \boldsymbol{z}_i \mid \boldsymbol{\theta})) \, d\boldsymbol{z}_i$$

$$\stackrel{(a)}{=} \max_{\boldsymbol{\theta}} \mathbb{E}_{\sim \boldsymbol{q}^{(t)}(\boldsymbol{z}_i)} \big[ \log \mathbb{P}(\boldsymbol{x}_i, \boldsymbol{z}_i \mid \boldsymbol{\theta}) \big],$$

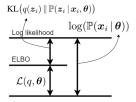
where (a) is because of definition of expectation. Thus, the M-step assigns:

$$\boldsymbol{\theta}^{(t)} \leftarrow \arg \max_{\boldsymbol{\theta}} \mathbb{E}_{\sim q^{(t)}(\boldsymbol{z}_i)} \big[ \log \mathbb{P}(\boldsymbol{x}_i, \boldsymbol{z}_i \mid \boldsymbol{\theta}) \big].$$
(11)

We found:

$$\boldsymbol{\theta}^{(t)} \leftarrow \arg \max_{\boldsymbol{\theta}} \ \mathbb{E}_{\sim q^{(t)}(\boldsymbol{z}_i)} \big[ \log \mathbb{P}(\boldsymbol{x}_i, \boldsymbol{z}_i \,|\, \boldsymbol{\theta}) \big].$$

• In other words, in the figure, it pushes the above line higher.



- The E-step and M-step together somehow play a **game** where the E-step tries to reach the middle line (or the ELBO) to the log-likelihood and the M-step tries to increase the above line (or the log-likelihood). This procedure is done repeatedly so the two steps help each other improve to higher values.
- To summarize, the EM in variational inference is:

$$q^{(t)}(\boldsymbol{z}_i) \leftarrow \mathbb{P}(\boldsymbol{z}_i \,|\, \boldsymbol{x}_i, \boldsymbol{\theta}^{(t-1)}), \tag{12}$$

$$\boldsymbol{\theta}^{(t)} \leftarrow \arg \max_{\boldsymbol{\theta}} \mathbb{E}_{\sim q^{(t)}(\boldsymbol{z}_i)} \big[ \log \mathbb{P}(\boldsymbol{x}_i, \boldsymbol{z}_i \mid \boldsymbol{\theta}) \big].$$
(13)

- It is noteworthy that, in variational inference, sometimes, the parameter θ is absorbed into the latent variable z<sub>i</sub>.
- According to the chain rule, we have:

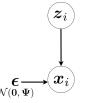
 $\mathbb{P}(\boldsymbol{x}_i, \boldsymbol{z}_i, \boldsymbol{\theta}) = \mathbb{P}(\boldsymbol{x}_i \mid \boldsymbol{z}_i, \boldsymbol{\theta}) \mathbb{P}(\boldsymbol{z}_i \mid \boldsymbol{\theta}) \mathbb{P}(\boldsymbol{\theta}).$ 

• Considering the term  $\mathbb{P}(\mathbf{z}_i | \boldsymbol{\theta}) \mathbb{P}(\boldsymbol{\theta})$  as one probability term, we have:

 $\mathbb{P}(\boldsymbol{x}_i, \boldsymbol{z}_i) = \mathbb{P}(\boldsymbol{x}_i \mid \boldsymbol{z}_i) \mathbb{P}(\boldsymbol{z}_i),$ 

where the parameter  $\theta$  disappears because of absorption.

- Factor analysis [2, 3, 4, 5] is one of the simplest and most fundamental generative models.
- Factor analysis assumes that every data point  $x_i \in \mathbb{R}^d$  is generated from a latent variable  $z_i \in \mathbb{R}^p$ . The **latent variable** is also referred to as the **latent factor**; hence, the name of factor analysis comes from the fact that it analyzes the latent factors.
- In factor analysis, we assume that the data point x<sub>i</sub> is obtained through the following steps: (1) by linear projection of the *p*-dimensional z<sub>i</sub> onto a *d*-dimensional space by projection matrix Λ ∈ ℝ<sup>d×p</sup>, then (2) applying some linear translation, and finally (3) adding a Gaussian noise ε ∈ ℝ<sup>d</sup> with covariance matrix Ψ ∈ ℝ<sup>d×d</sup>.
- Note that as the noises in different dimensions are independent, the covariance matrix Ψ is diagonal.
- Factor analysis can be illustrated as a graphical model [6] where the visible data variable is conditioned on the latent variable and the noise random variable.



 For simplicity, the prior distribution of the latent variable can be assumed to be a multivariate Gaussian distribution:

$$\mathbb{P}(\boldsymbol{z}_i) = \mathcal{N}(\boldsymbol{z}_i \mid \boldsymbol{\mu}_0, \boldsymbol{\Sigma}_0) = \frac{1}{\sqrt{(2\pi)^p |\boldsymbol{\Sigma}_0|}} \exp\left(-\frac{(\boldsymbol{z}_i - \boldsymbol{\mu}_0)^\top \boldsymbol{\Sigma}_0^{-1} (\boldsymbol{z}_i - \boldsymbol{\mu}_0)}{2}\right), \quad (14)$$

where  $\mu_0 \in \mathbb{R}^{\rho}$  and  $\Sigma_0 \in \mathbb{R}^{\rho \times \rho}$  are the mean and the covariance matrix of  $z_i$  and |.| is the determinant of matrix.

- x<sub>i</sub> is obtained through (1) the linear projection of z<sub>i</sub> by Λ ∈ ℝ<sup>d×p</sup>, (2) applying some linear translation, and (3) adding a Gaussian noise ε ∈ ℝ<sup>d</sup> with covariance Ψ ∈ ℝ<sup>d×d</sup>.
- Hence, the data point x<sub>i</sub> has a **conditional multivariate Gaussian distribution given the latent variable**; its conditional likelihood is:

$$\mathbb{P}(\mathbf{x}_i \mid \mathbf{z}_i) = \mathbb{P}(\mathbf{x}_i \mid \mathbf{z}_i, \mathbf{\Lambda}, \boldsymbol{\mu}, \boldsymbol{\Psi}) = \mathcal{N}(\mathbf{\Lambda}\mathbf{z}_i + \boldsymbol{\mu}, \boldsymbol{\Psi}),$$
(15)

where  $\mu$ , which is the translation vector, is the mean of data  $\{x_i\}_{i=1}^n$ :

$$\mathbb{R}^d \ni \boldsymbol{\mu} := \frac{1}{n} \sum_{i=1}^n \boldsymbol{x}_i.$$
 (16)

• The marginal distribution of x<sub>i</sub> is:

$$\mathbb{P}(\mathbf{x}_{i}) = \int \mathbb{P}(\mathbf{x}_{i} | \mathbf{z}_{i}) \mathbb{P}(\mathbf{z}_{i}) d\mathbf{z}_{i} \implies$$

$$\mathbb{P}(\mathbf{x}_{i} | \mathbf{\Lambda}, \boldsymbol{\mu}, \boldsymbol{\Psi}) = \int \mathbb{P}(\mathbf{x}_{i} | \mathbf{z}_{i}, \mathbf{\Lambda}, \boldsymbol{\mu}, \boldsymbol{\Psi}) \mathbb{P}(\mathbf{z}_{i} | \boldsymbol{\mu}_{0}, \boldsymbol{\Sigma}_{0}) d\mathbf{z}_{i}$$

$$\stackrel{(a)}{=} \mathcal{N}(\mathbf{\Lambda}\boldsymbol{\mu}_{0} + \boldsymbol{\mu}, \boldsymbol{\Psi} + \mathbf{\Lambda}\boldsymbol{\Sigma}_{0}\mathbf{\Lambda}^{\top}) \qquad (17)$$

$$= \mathcal{N}(\hat{\boldsymbol{\mu}}, \boldsymbol{\Psi} + \widehat{\mathbf{\Lambda}}\widehat{\mathbf{\Lambda}}^{\top}), \qquad (18)$$

where  $\mathbb{R}^d \ni \widehat{\mu} := \Lambda \mu_0 + \mu$ ,  $\mathbb{R}^{d \times d} \ni \widehat{\Lambda} := \Lambda \Sigma_0^{(1/2)}$ , and (a) is because mean is linear and variance is quadratic so the mean and variance of projection are applied linearly and quadratically, respectively.

- As the mean  $\hat{\mu}$  and covariance  $\hat{\Lambda}$  are needed to be learned, we can absorb  $\mu_0$  and  $\Sigma_0$  into  $\mu$  and  $\Lambda$  and assume that  $\mu_0 = 0$  and  $\Sigma_0 = I$ .
- In summary, factor analysis assumes every data point  $x_i \in \mathbb{R}^d$  is obtained by projecting a latent variable  $z_i \in \mathbb{R}^p$  onto a *d*-dimensional space by projection matrix  $\mathbf{\Lambda} \in \mathbb{R}^{d \times p}$  and translating it by  $\boldsymbol{\mu} \in \mathbb{R}^d$  and finally adding some Gaussian noise  $\boldsymbol{\epsilon} \in \mathbb{R}^d$  (whose dimensions are independent) as:

$$\mathbf{x}_i := \mathbf{\Lambda} \mathbf{z}_i + \boldsymbol{\mu} + \boldsymbol{\epsilon}, \tag{19}$$

$$\mathbb{P}(\boldsymbol{z}_i) = \mathcal{N}(\boldsymbol{0}, \boldsymbol{I}), \tag{20}$$

$$\mathbb{P}(\epsilon) = \mathcal{N}(\mathbf{0}, \mathbf{\Psi}). \tag{21}$$

• The joint distribution of  $x_i$  and  $z_i$  is:

$$\mathbf{y}_i := \begin{bmatrix} \mathbf{x}_i \\ \mathbf{z}_i \end{bmatrix} \sim \mathcal{N}(\boldsymbol{\mu}_y, \boldsymbol{\Sigma}_y).$$
(22)

• The expectation of **x**<sub>i</sub> is:

$$\mathbb{E}[\mathbf{x}_i] \stackrel{(19)}{=} \mathbb{E}[\mathbf{\Lambda}\mathbf{z}_i + \boldsymbol{\mu} + \boldsymbol{\epsilon}] = \mathbf{\Lambda}\mathbb{E}[\mathbf{z}_i] + \boldsymbol{\mu} + \mathbb{E}[\boldsymbol{\epsilon}] \stackrel{(a)}{=} \boldsymbol{\mu},$$
(23)

where (*a*) is because of Eqs. (20) and (21). • Hence:

 $\boldsymbol{\mu}_{\boldsymbol{y}} := \begin{bmatrix} \boldsymbol{\mu}_{\boldsymbol{x}} \\ \boldsymbol{\mu}_{\boldsymbol{z}} \end{bmatrix} \stackrel{(a)}{=} \begin{bmatrix} \boldsymbol{\mu} \\ \boldsymbol{0} \end{bmatrix}, \qquad (24)$ 

where (a) is because of Eqs. (20) and (23).

Lemma:

#### Lemma

Consider two random variables  $\mathbf{x}_i \in \mathbb{R}^d$  and  $\mathbf{z}_i \in \mathbb{R}^p$  and let  $\mathbf{y}_i := [\mathbf{x}_i^\top, \mathbf{z}_i^\top]^\top \in \mathbb{R}^{d+p}$ . Assume that  $\mathbf{x}_i$  and  $\mathbf{z}_i$  are jointly multivariate Gaussian; hence, the variable  $\mathbf{y}_i$  has a multivariate Gaussian distribution, i.e.,  $\mathbf{y}_i \sim \mathcal{N}(\boldsymbol{\mu}_{\mathbf{v}}, \boldsymbol{\Sigma}_{\mathbf{y}})$ . The mean and covariance can be decomposed as:

$$\boldsymbol{\mu}_{\boldsymbol{y}} = [\boldsymbol{\mu}^{\top}, \boldsymbol{\mu}_{0}^{\top}]^{\top} \in \mathbb{R}^{d+p}, \tag{25}$$

$$\mathbf{\Sigma}_{y} = \begin{bmatrix} \mathbf{\Sigma}_{11} & \mathbf{\Sigma}_{12} \\ \mathbf{\Sigma}_{21} & \mathbf{\Sigma}_{22} \end{bmatrix} \in \mathbb{R}^{(d+p) \times (d+p)},$$
(26)

where  $\mu \in \mathbb{R}^d$ ,  $\mu_0 \in \mathbb{R}^p$ ,  $\Sigma_{11} \in \mathbb{R}^{d \times d}$ ,  $\Sigma_{22} \in \mathbb{R}^{p \times p}$ ,  $\Sigma_{12} \in \mathbb{R}^{d \times p}$ , and  $\Sigma_{21} = \Sigma_{12}^{\top} \in \mathbb{R}^{p \times d}$ .

• Lemma [7]:

#### Lemma

$$\mathbb{R}^d \ni \boldsymbol{\mu}_{x|z} := \boldsymbol{\mu} + \boldsymbol{\Sigma}_{12} \boldsymbol{\Sigma}_{22}^{-1} (\boldsymbol{z}_i - \boldsymbol{\mu}_0), \tag{27}$$

$$\mathbb{R}^{d \times d} \ni \mathbf{\Sigma}_{x|z} := \mathbf{\Sigma}_{11} - \mathbf{\Sigma}_{12} \mathbf{\Sigma}_{22}^{-1} \mathbf{\Sigma}_{21}, \tag{28}$$

and likewise for  $\mathbf{z}_i | \mathbf{x}_i \sim \mathcal{N}(\boldsymbol{\mu}_{z|x}, \boldsymbol{\Sigma}_{z|x})$ :

$$\mathbb{R}^{p} \ni \boldsymbol{\mu}_{z|x} := \boldsymbol{\mu}_{0} + \boldsymbol{\Sigma}_{21} \boldsymbol{\Sigma}_{11}^{-1} (\boldsymbol{x}_{i} - \boldsymbol{\mu}), \tag{29}$$

$$\mathbb{R}^{p \times p} \ni \mathbf{\Sigma}_{z|x} := \mathbf{\Sigma}_{22} - \mathbf{\Sigma}_{21} \mathbf{\Sigma}_{11}^{-1} \mathbf{\Sigma}_{12}.$$
 (30)

• According to Eq. (20), we have  $\Sigma_{22} = \Sigma_z = I$ . According to Eq. (19), we have:

$$\begin{split} \boldsymbol{\Sigma}_{11} &= \boldsymbol{\Sigma}_{\mathbf{x}} = \mathbb{E}[(\boldsymbol{x}_{i} - \boldsymbol{\mu})(\boldsymbol{x}_{i} - \boldsymbol{\mu})^{\top}] \\ &= \mathbb{E}[(\boldsymbol{\Lambda}\boldsymbol{z}_{i} + \boldsymbol{\mu} + \boldsymbol{\epsilon} - \boldsymbol{\mu})(\boldsymbol{\Lambda}\boldsymbol{z}_{i} + \boldsymbol{\mu} + \boldsymbol{\epsilon} - \boldsymbol{\mu})^{\top}] \\ &= \mathbb{E}[\boldsymbol{\Lambda}\boldsymbol{z}_{i}\boldsymbol{z}_{i}^{\top}\boldsymbol{\Lambda}^{\top} + \boldsymbol{\epsilon}\boldsymbol{z}_{i}^{\top}\boldsymbol{\Lambda}^{\top} + \boldsymbol{\Lambda}\boldsymbol{z}_{i}\boldsymbol{\epsilon}^{\top} + \boldsymbol{\epsilon}\boldsymbol{\epsilon}^{\top}] \\ &= \boldsymbol{\Lambda}\mathbb{E}[\boldsymbol{z}_{i}\boldsymbol{z}_{i}^{\top}]\boldsymbol{\Lambda}^{\top} + \mathbb{E}[\boldsymbol{\epsilon}]\mathbb{E}[\boldsymbol{z}_{i}]^{\top}\boldsymbol{\Lambda}^{\top} + \boldsymbol{\Lambda}\mathbb{E}[\boldsymbol{z}_{i}]\mathbb{E}[\boldsymbol{\epsilon}]^{\top} + \mathbb{E}[\boldsymbol{\epsilon}\boldsymbol{\epsilon}^{\top}] \\ &\stackrel{(a)}{=} \boldsymbol{\Lambda}\boldsymbol{\Lambda}\boldsymbol{\Lambda}^{\top} + \boldsymbol{0} + \boldsymbol{0} + \boldsymbol{\Psi} = \boldsymbol{\Lambda}\boldsymbol{\Lambda}^{\top} + \boldsymbol{\Psi}, \end{split}$$
(31)

where (a) is because of Eqs. (20) and (21).

Moreover, we have:

$$\Sigma_{12} = \Sigma_{xz} = \mathbb{E}[(\mathbf{x}_i - \boldsymbol{\mu})(\mathbf{z}_i - \boldsymbol{\mu}_0)^{\top}]$$

$$\stackrel{(a)}{=} \mathbb{E}[(\mathbf{\Lambda}\mathbf{z}_i + \boldsymbol{\mu} + \boldsymbol{\epsilon} - \boldsymbol{\mu})(\mathbf{z}_i - \mathbf{0})^{\top}]$$

$$\stackrel{(b)}{=} \mathbf{\Lambda}\mathbb{E}[\mathbf{z}_i \mathbf{z}_i^{\top}] + \mathbb{E}[\boldsymbol{\epsilon}]\mathbb{E}[\mathbf{z}_i^{\top}] = \mathbf{\Lambda}\mathbf{I} + (\mathbf{0}\mathbf{0}^{\top}) = \mathbf{\Lambda}, \qquad (32)$$

where (a) is because of Eqs. (19) and (20) and (b) is because  $z_i$  and  $\epsilon$  are independent. • We also have  $\Sigma_{21} = \Sigma_{12}^{\top} = \Lambda^{\top}$ . Therefore:

$$\begin{bmatrix} \mathbf{x}_i \\ \mathbf{z}_i \end{bmatrix} \sim \mathcal{N} \left( \begin{bmatrix} \boldsymbol{\mu} \\ \mathbf{0} \end{bmatrix}, \begin{bmatrix} \mathbf{\Lambda} \mathbf{\Lambda}^\top + \mathbf{\Psi} & \mathbf{\Lambda} \\ \mathbf{\Lambda}^\top & \mathbf{I} \end{bmatrix} \right).$$
(33)

• Hence, the marginal distribution of data point x<sub>i</sub> is:

$$\mathbb{P}(\boldsymbol{x}_i) = \mathbb{P}(\boldsymbol{x}_i \mid \boldsymbol{\Lambda}, \boldsymbol{\mu}, \boldsymbol{\Psi}) = \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Lambda}\boldsymbol{\Lambda}^\top + \boldsymbol{\Psi}). \tag{34}$$

According to Eqs. (29) and (30) [Lemma], the posterior or the conditional distribution of latent variable given data is:

$$q(\mathbf{z}_i) \stackrel{(12)}{=} \mathbb{P}(\mathbf{z}_i \mid \mathbf{x}_i) = \mathbb{P}(\mathbf{z}_i \mid \mathbf{x}_i, \mathbf{\Lambda}, \boldsymbol{\mu}, \boldsymbol{\Psi}) = \mathcal{N}(\boldsymbol{\mu}_{z \mid x}, \boldsymbol{\Sigma}_{z \mid x}),$$
(35)

where:

$$\mathbb{R}^{p} \ni \boldsymbol{\mu}_{z|x} := \boldsymbol{\Lambda}^{\top} (\boldsymbol{\Lambda} \boldsymbol{\Lambda}^{\top} + \boldsymbol{\Psi})^{-1} (\boldsymbol{x}_{i} - \boldsymbol{\mu}),$$
(36)

$$\mathbb{R}^{p \times p} \ni \mathbf{\Sigma}_{z|x} := \mathbf{I} - \mathbf{\Lambda}^{\top} (\mathbf{\Lambda} \mathbf{\Lambda}^{\top} + \mathbf{\Psi})^{-1} \mathbf{\Lambda}.$$
(37)

• Recall that the conditional distribution of data given the latent variable, i.e.  $\mathbb{P}(x_i | z_i)$ , was introduced in Eq. (15):

$$\mathbb{P}(\boldsymbol{x}_i \mid \boldsymbol{z}_i) = \mathbb{P}(\boldsymbol{x}_i \mid \boldsymbol{z}_i, \boldsymbol{\Lambda}, \boldsymbol{\mu}, \boldsymbol{\Psi}) = \mathcal{N}(\boldsymbol{\Lambda} \boldsymbol{z}_i + \boldsymbol{\mu}, \boldsymbol{\Psi}).$$

If data  $\{x_i\}_{i=1}^n$  are centered, i.e.  $\mu = \mathbf{0}$ , the marginal of data, Eq. (34), and the likelihood of data, Eq. (15), become:

$$\mathbb{P}(\mathbf{x}_i \,|\, \mathbf{\Lambda}, \mathbf{\Psi}) = \mathcal{N}(\mathbf{0}, \mathbf{\Psi} + \mathbf{\Lambda} \mathbf{\Lambda}^{\top}), \tag{38}$$

$$\mathbb{P}(\boldsymbol{x}_i \,|\, \boldsymbol{z}_i, \boldsymbol{\Lambda}, \boldsymbol{\Psi}) = \mathcal{N}(\boldsymbol{\Lambda} \boldsymbol{z}_i, \boldsymbol{\Psi}), \tag{39}$$

respectively. In some works, people center the data as a pre-processing to factor analysis.

- We can find the parameters  $\Lambda$  and  $\Psi$  using Expectation Maximization.
- See our tutorial "Factor analysis, probabilistic principal component analysis, variational inference, and variational autoencoder: Tutorial and survey" [8] for the details of EM steps in factor analysis.

Probabilistic Principal Component Analysis

## Probabilistic Principal Component Analysis

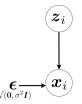
• Probabilistic PCA (PPCA) (1997-1999) [9, 10] is a special case of factor analysis where the variance of noise is equal in all dimensions of data space with covariance between dimensions, i.e.:

$$\Psi = \sigma^2 I. \tag{40}$$

In other words, PPCA considers an isotropic noise in its formulation. Therefore, Eq. (21) is simplified to:

$$\mathbb{P}(\boldsymbol{\epsilon}) = \mathcal{N}(\boldsymbol{0}, \sigma^2 \boldsymbol{I}). \tag{41}$$

- Because of having zero covariance of noise between different dimensions, PPCA assumes that the data points are **independent** of each other given latent variables.
- PPCA can be illustrated as a graphical model, where the visible data variable is conditioned on the latent variable and the isotropic noise random variable.



# Probabilistic Principal Component Analysis

- As PPCA is a special case of factor analysis, it also is solved using EM. Similar to factor analysis, it can be solved iteratively using EM [9].
- However, one can also find a closed-form solution to its EM approach [10]. Hence, by restricting the noise covariance to be isotropic, its solution becomes simpler and closed-form.
- We can find the parameters  $\Lambda$  and  $\sigma$  using Expectation Maximization.
- See our tutorial "Factor analysis, probabilistic principal component analysis, variational inference, and variational autoencoder: Tutorial and survey" [8] for the details of EM steps in PPCA.

# Acknowledgment

- Some slides are based on our tutorial paper: "Factor analysis, probabilistic principal component analysis, variational inference, and variational autoencoder: Tutorial and survey" [8]
- Some slides of this slide deck are inspired by teachings of deep learning course at the Carnegie Mellon University (you can see their YouTube channel).
- Factor analysis in sklearn: https://scikit-learn.org/stable/modules/generated/ sklearn.decomposition.FactorAnalysis.html

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